

## Research Article

# Global Behavior of a New Rational Nonlinear Higher-Order Difference Equation

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Let  $k$  be a nonnegative integer and  $c$  a real number greater than or equal to 1. We present qualitative global behavior of solutions to a rational nonlinear higher-order difference equation  $z_{n+1} = (c(z_n + z_{n-k}) + (c-1)z_n z_{n-k}) / (z_n z_{n-k} + c)$ ,  $n \geq 0$ , with positive initial values  $z_{-k}, z_{-k+1}, \dots, z_0$ , and show the global asymptotic stability of its positive equilibrium solution.

## 1. Introduction

Difference equations have wide applications in biology, computer science, digital signal processing, and economics. A general solution structure exists for linear difference equations [1]. However, in various situations of nonlinear higher-order difference equations, solution properties can only be observed by numerical simulation, and it is often exceedingly difficult to give a full mathematical proof for the properties predicted by numerical simulation and the conclusions formed on the basis of guesswork [2]. It is, therefore, important to make qualitative analysis on nonlinear higher-order difference equations, which is the topic of the current study. There have been some related studies on rational nonlinear difference equations in the literature (see, e.g., [3–8]). Global asymptotic properties of spectral functions are also crucial in determining algebro-geometric solutions of soliton equations (see, e.g., [9, 10]) and scattering data in matrix spectral problems (see, e.g., [11]).

An iterative algorithm to approximate a zero of a given function  $f$  reads

$$x_{n+1} = \frac{x_{n-1}f(x_n) - x_nf(x_{n-1})}{f(x_n) - f(x_{n-1})}, \quad n \geq 0, \quad (1)$$

and an application of this to a quadratic function  $f(x) = x^2 - a$ ,  $a > 0$ , gives

$$x_{n+1} = \frac{x_n x_{n-1} + a}{x_n + x_{n-1}}, \quad n \geq 0. \quad (2)$$

Let  $k$  be a nonnegative integer and  $c$  a real number greater than or equal to 1. We would like to consider a more general rational nonlinear higher-order difference equation

$$z_{n+1} = \frac{c(z_n + z_{n-k}) + (c-1)z_n z_{n-k}}{z_n z_{n-k} + c}, \quad n \geq 0, \quad (3)$$

with positive initial values  $z_{-k}, z_{-k+1}, \dots, z_0$ , which engender positive solutions. We take a transformation

$$z_n = \frac{c}{y_n}, \quad n \geq -k, \quad (4)$$

and then obtain another difference equation

$$y_{n+1} = \frac{y_n y_{n-k} + c}{y_n + y_{n-k} + c - 1}, \quad n \geq 0, \quad (5)$$

Obviously, the equilibrium solution of the rational nonlinear difference equation (3),  $\bar{z} = c$ , becomes the equilibrium solution of the transformed difference equation (5),  $\bar{y} = 1$ .

If we further take  $c = 1$ , then we obtain the nonlinear difference equation discussed in [6, 7]:

$$y_{n+1} = \frac{y_n y_{n-k} + 1}{y_n + y_{n-k}}, \quad n \geq 0. \quad (6)$$

Introducing  $x_n = \sqrt{a} y_n$  into (6) yields

$$x_{n+1} = \frac{x_n x_{n-k} + a}{x_n + x_{n-k}}, \quad n \geq 0, \quad (7)$$

where  $a > 0$ . When  $k = 1$ , this gives the nonlinear difference equation in (2). The equation (7) in the case of  $k = 2$  was studied in [5] and its closed-form solution was presented in [6]. In the general case of  $k$ , the asymptotic stability of the positive equilibrium solution  $\bar{x} = 1$  of the equation (7) was proved in [7].

It is direct to see that the rational nonlinear higher-order difference equation, defined by (3), possesses three equilibria:  $\bar{z} = -1, 0, c$ . In this article, we would like to explore global behavior of solutions to the rational nonlinear higher-order difference equation (3), show the global asymptotic stability of its positive equilibrium solution  $\bar{z} = c$ , and present two illustrative examples of positive solutions.

## 2. Global Behavior

**2.1. Classification of Solutions.** First of all, based on the rational difference equation (3), one can have

$$z_{n+1} - c = \frac{(c - z_{n-k})(z_n - c)}{z_n z_{n-k} + c}, \quad n \geq 0, \quad (8)$$

$$z_{n+1} - z_n = \frac{z_{n-k}(z_n + 1)(c - z_n)}{z_n z_{n-k} + c}, \quad n \geq 0, \quad (9)$$

$$z_{n+1} - z_{n-k} = \frac{z_n(z_{n-k} + 1)(c - z_{n-k})}{z_n z_{n-k} + c}, \quad n \geq 0. \quad (10)$$

Further from (9) and (10), we can easily derive the following solution properties.

**Theorem 1.** *If  $\{z_n\}_{n=-k}^{\infty}$  is a solution to the rational nonlinear difference equation (3), then one has*

$$z_{n+1} < z_n \quad \text{if } z_n > c, \quad (11)$$

$$z_{n+1} > z_n \quad \text{if } z_n < c,$$

$$z_{n+1} < z_{n-k} \quad \text{if } z_{n-k} > c, \quad (12)$$

$$z_{n+1} > z_{n-k} \quad \text{if } z_{n-k} < c,$$

where  $n \geq 0$ .

If  $k = 0$ , the rational difference equation (3) becomes a first-order difference equation

$$z_{n+1} = \frac{2cz_n + (c-1)z_n^2}{z_n^2 + c}, \quad n \geq 0. \quad (13)$$

Then for  $n \geq 0$ , one has  $z_{n+1} \leq c$ , because  $-z_n^2 + 2cz_n \leq c^2$ . For  $n \geq 1$ , one has  $z_{n+1} \geq z_n$ , since  $(c-1)z_n + c \geq z_n^2$ , due to  $z_n \leq c$ . Therefore, every solution  $z_n$  decays to  $c$ , when  $n \rightarrow \infty$ .

Generally, there are three types of solutions to the rational nonlinear higher-order difference equation (3).

**Theorem 2.** *Let  $k \geq 1$ . If  $\{z_n\}_{n=-k}^{\infty}$  is a solution to the rational nonlinear higher-order difference equation (3), and then*

(a) *it is eventually equal to  $c$ , more precisely  $z_n = c, n \geq m$ , which occurs when  $z_m = c$  for some  $m \geq 0$ ;*

(b) *it is eventually less than  $c$ , more precisely  $z_n < z_{n+1} < c, n \geq m+k$ , which occurs when  $z_m, z_{m+1}, \dots, z_{m+k} < c$  for some  $m \geq -k$ ; or*

(c) *it oscillates about  $c$ , possessing at most  $k$  consecutive increasing terms less than  $c$  and at most  $k+1$  consecutive decreasing terms greater than  $c$ .*

*Proof.* Equality (8) and property (11) directly tell that we have three types of solutions to the rational nonlinear higher-order difference equation (3).

The decreasing and increasing characteristics of oscillatory solutions in the third solution situation (c) can be proved as follows.

Suppose that  $n_1, n_2 \geq 0$  are two integers satisfying  $n_1 < n_2$ . We express

$$\begin{aligned} z_{n_2} - z_{n_1} &= (z_{n_2} - z_{n_2-1}) + (z_{n_2-1} - z_{n_2-2}) + \dots \\ &\quad + (z_{n_1+1} - z_{n_1}) = D, \end{aligned} \quad (14)$$

where  $D$  can be written as

$$D = \sum_{j=n_1}^{n_2-1} \frac{z_{j-k}(c - z_j)(z_j + 1)}{z_j z_{j-k} + c}, \quad (15)$$

by (9).

If  $z_n > c$  for  $n_1 \leq n \leq n_2$ , then each term in  $D$  is less than zero, and so  $z_{n_2} < z_{n_1}$ , due to (14). If  $z_n < c$  for  $n_1 \leq n \leq n_2$ , then each term in  $D$  is greater than zero, and so  $z_{n_2} > z_{n_1}$ , due to (14). This completes the proof.  $\square$

Note that based on (8), we can see that there is no solution situation that a solution of (3) is eventually greater than  $c$ .

**2.2. Global Asymptotic Stability.** When  $k = 0$ , the equilibrium solution  $\bar{z} = c$  of the first-order rational difference equation (13) is globally asymptotically stable, since it is a globally attractive equilibrium solution of a first-order difference equation (see [12] for a general theory).

For a general  $k \geq 1$ , we can show the same global asymptotic stability of the positive equilibrium solution  $\bar{z} = c$  of the rational nonlinear difference equation (3), by establishing the local asymptotic stability and the global attractivity, which imply the global asymptotic stability [2]. Instead, we establish a strong negative feedback property [13] to guarantee the global asymptotic stability of  $\bar{z} = c$  (see [14] for details on the strong negative feedback property).

**Theorem 3.** *The positive equilibrium solution  $\bar{z} = c$  of the rational nonlinear higher-order difference equation (3) is globally asymptotically stable.*

*Proof.* Based on the rational nonlinear difference equation (3), one can have

$$\begin{aligned} \frac{c^2}{z_{n-k}} - z_{n+1} &= \frac{(c - z_{n-k})[(c - 1)z_n z_{n-k} + c z_{n-k} + c^2]}{z_{n-k}(z_n z_{n-k} + c)}, \quad (16) \\ n &\geq 0. \end{aligned}$$

From this equality and the equality in (10), we can obtain

$$\begin{aligned} (z_{n-k} - z_{n+1}) \left( \frac{c^2}{z_{n-k}} - z_{n+1} \right) &= - \frac{z_n (z_{n-k} + 1) (c - z_{n-k})^2 [(c - 1)z_n z_{n-k} + c z_{n-k} + c^2]}{z_{n-k} (z_n z_{n-k} + c)^2}, \quad (17) \\ n &\geq 0, \end{aligned}$$

which leads to a strong negative feedback property:

$$(z_{n-k} - z_{n+1}) \left( \frac{c^2}{z_{n-k}} - z_{n+1} \right) \leq 0, \quad n \geq 0, \quad (18)$$

with equality for all  $n \geq 0$  if and only if  $z_n = c, n \geq -k$ . It, therefore, follows from a stability theorem (Corollary 3 of [14]) that the equilibrium solution  $\bar{z} = c$  of the rational nonlinear difference equation (3) is globally asymptotically stable. Thus, the proof is finished.  $\square$

The above theorems with  $c = 1$  gives the results in [4] ( $k = 1$ ), [5] ( $k = 2$ ) and [7] (a general  $k$ ). There have also been similar studies on polynomial difference equations (see, for example, [15]) and other studies on positive rational function solutions, called lumps, to partial differential equations (see, e.g., [16]).

**2.3. Illustrative Examples and an Open Question.** To illustrate the global properties stated in Theorems 2 and 3, here we present two illustrative examples associated with two special cases:

$$\begin{aligned} c &= \frac{3}{2}, \\ k &= 3, \\ z_{-3} &= \frac{6}{5}, \\ z_{-2} &= \frac{16}{9}, \\ z_{-1} &= \frac{10}{7}, \end{aligned}$$

$$\begin{aligned} z_0 &= 1; \\ c &= 2, \\ k &= 5, \\ z_{-5} &= \frac{5}{4}, \\ z_{-4} &= \frac{7}{3}, \\ z_{-3} &= \frac{5}{3}, \\ z_{-2} &= \frac{9}{4}, \\ z_{-1} &= \frac{3}{2}, \\ z_0 &= \frac{7}{3}; \end{aligned} \quad (19)$$

in Figure 1. From the plot pictures, we see that the convergence is achieved very fast in both cases.

Finally, let  $k \geq 1$ . For an oscillatory solution  $\{z_n\}_{n=-k}^{\infty}$  of the rational nonlinear difference equation (3), we define

$$\begin{aligned} N_g &= \{n \mid z_n > c \text{ and } n \geq 0\}, \\ N_l &= \{n \mid z_n < c \text{ and } n \geq 0\}. \end{aligned} \quad (20)$$

Since  $\{z_n\}_{n=-k}^{\infty}$  is oscillatory, Theorem 2 guarantees that both  $N_g$  and  $N_l$  have infinitely many numbers. A basic open question that we are very interested in is if  $z_n$  is decreasing on  $N_g$  and increasing on  $N_l$ . We point out that through the above two examples, we failed to find any counterexample to this statement, but found that two cases could occur: either  $z_{n-1}, z_{n+1} < c$  but  $z_n > c$  or  $z_{n-1}, z_{n+1} > c$  but  $z_n < c$  for some  $n > 1$ .

## Data Availability

The data used to support the findings of this study are included within the article.

## Conflicts of Interest

The authors declare that there are no conflicts of interest regarding the publication of this paper.

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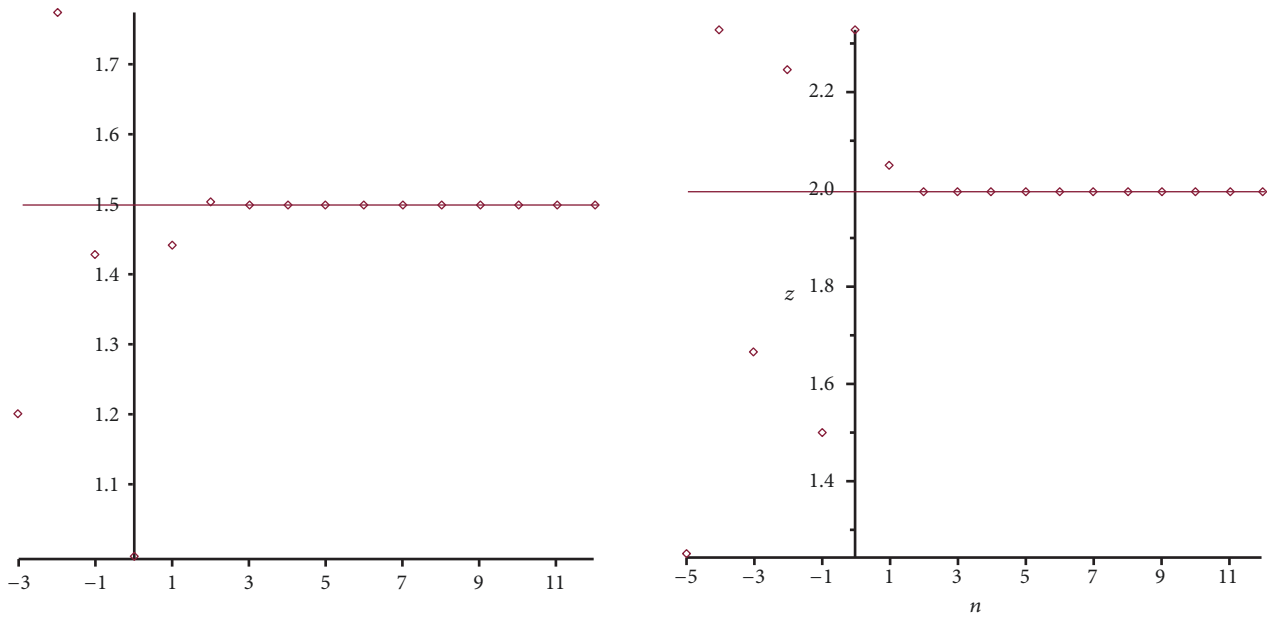


FIGURE 1: Profiles of  $\{z_n\}_{n=-k}^{\infty}$  with  $c = 3/2$ ,  $k = 3$  (left) and  $c = 2$ ,  $k = 5$  (right).

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