

Recent results on multiscale technique and integrability of partial difference equations

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1 Introduction

- Multiscale analysis and Integrability for PDEs
- Multiscale on the lattice
 - from shifts to derivatives
 - from derivative to shifts

2 Integrability of discrete Nonlinear Schrödinger Equations

3 Other examples

4 Classification of lattice equations on the square

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Introduction

- Multiscale analysis: perturbation technique for constructing *uniformly* valid approximation to solutions of perturbation problems;
- *Nonuniformity* arises from *secularity*.
- Multiscale perturbation methods have been introduced by Poincaré to deal with secularity problems in the perturbative solution of differential equations.
- In the reductive perturbation method introduced by Taniuti et. al., the *space and time coordinates are stretched* in terms of a small expansion parameter and we look for the far field behaviour of the system.
- Multi-scale expansions can be applied to both *integrable* and *non-integrable systems*.

Multiscale analysis and integrability

- Multiscale analysis: perturbation technique for testing *integrability* of a given nonlinear system [Calogero];
- *Integrability* is *preserved* in the reduction process [Zakharov, Kuznetsov PDE].
- Partial differential equation example: *KdV* equation for $u(x, t) \in \mathcal{R}$

$$\frac{\partial u}{\partial t} + \frac{\partial^3 u}{\partial x^3} = u \frac{\partial u}{\partial x}.$$

- Solution of the form

$$u(x, t; \varepsilon) = \sum_{n=1}^{+\infty} \sum_{\alpha=-n}^n \varepsilon^n u_n^{(\alpha)}(\xi, t_1, t_2, \dots) e^{i\alpha(\kappa x - \omega t)}.$$

$u_n^{(-\alpha)} = \bar{u}_n^{(\alpha)}$. $\xi \doteq \varepsilon x$, $t_j \doteq \varepsilon^j t$, $j \geq 1$ are the *slow variables*;

Multiscale analysis and integrability

- Space and time partial derivatives becomes:

$$\partial_x \rightarrow \partial_x + \varepsilon \partial_\xi,$$

$$\partial_t \rightarrow \partial_t + \varepsilon \partial_{t_1} + \varepsilon^2 \partial_{t_2} + \dots,$$

and all the variables are considered to be *independent*;

- Order ε :

$$\alpha = 1: \text{dispersion relation } \omega = -\kappa^3;$$

- Order ε^2 :

$$\alpha = 0:$$

$$\partial_{t_1} u_1^{(0)} = 0.$$

$$\alpha = 1:$$

$$\left[\partial_{t_1} + i\kappa \left(3i\kappa \partial_\xi - u_1^{(0)} \right) \right] u_1^{(1)} = 0.$$

Solution:

$$u_1^{(1)} = g_1^{(1)}(\rho, t_2, t_3) e^{-\frac{i}{3\kappa} \int_{\xi_0}^{\xi} u_1^{(0)}(\xi', t_2, t_3) d\xi'}, \quad \rho \doteq \xi + 3\kappa^2 t_1.$$

Multiscale analysis and integrability

$\alpha = 2$:

$$u_2^{(2)} = -\frac{1}{6\kappa^2} \left(u_1^{(1)} \right)^2;$$

- Order ε^3 :

$\alpha = 0$:

$$\partial_{t_1} u_2^{(0)} = \partial_\rho \left(|u_1^{(1)}|^2 \right) + \frac{1}{2} \partial_\xi \left[\left(u_1^{(0)} \right)^2 \right] - \partial_{t_2} u_1^{(0)}.$$

No-secularity conditions

- The right-hand side solves the homogeneous equation: **secularity!**

$$\partial_{t_1} u_2^{(0)} = \partial_\rho \left(|u_1^{(1)}|^2 \right),$$

$$\left(\partial_{t_2} - u_1^{(0)} \partial_\xi \right) u_1^{(0)} = 0, \quad \text{Hopf equation: wave breaking!}$$

Solutions:

$$u_2^{(0)} = \frac{|u_1^{(1)}|^2}{3\kappa^2}, \quad u_1^{(0)} = 0.$$

$\alpha = 1$:

$$(\partial_{t_1} - 3\kappa^2 \partial_\xi) u_2^{(1)} = - \left(\partial_{t_2} + 3i\kappa \partial_\rho^2 - \frac{i}{6\kappa} |u_1^{(1)}|^2 \right) u_1^{(1)}.$$

No-secularity condition

- The right-hand side solves the homogeneous equation: **secularity!**

$$(\partial_{t_1} - 3\kappa^2 \partial_\xi) u_2^{(1)} = 0,$$

$$\left(\partial_{t_2} + 3i\kappa \partial_\rho^2 - \frac{i}{6\kappa} |u_1^{(1)}|^2 \right) u_1^{(1)} = 0 : \quad \text{NLS equation.}$$

- KdV* equation and *NLS* equation are **both integrable!**

Multiscale analysis and integrability

- Higher orders beyond NLS equation [Degasperis, Manakov, Santini]: *fundamental* for an integrability test.

Proposition [Degasperis, Procesi]: *If an equation is integrable, then under a multiscale expansion the functions $u_m^{(1)}$, $m \geq 1$ satisfy the equations*

$$\partial_{t_n} u_1^{(1)} = K_n \left[u_1^{(1)} \right],$$

$$M_n u_j^{(1)} = g_n(j), \quad M_n \doteq \partial_{t_n} - K_n' \left[u_1^{(1)} \right],$$

$\forall j, n \geq 2.$

$K_n \left[u_1^{(1)} \right]$: n -th flow in a hierarchy of *integrable* equations;

$K_n' \left[u_j^{(1)} \right] v$: Frechet derivative of $K_n[u_j^{(1)}]$ along v : *linearization*;

$g_n(j)$: nonhomogeneous forcing term in a well defined polynomial vector space or *linear* combination of basic monomials.

Multiscale analysis and integrability

- *Compatibility* conditions:

$$M_k g_n(j) = M_n g_k(j), \quad \forall k, n \geq 2.$$

- *Integrability* conditions: set of relations among the coefficients of $g_n(j)$.
- *Definition* [Degasperis, Procesi]: *If the compatibility conditions are satisfied up to the index $j \geq 2$, our equation is **asymptotically integrable** of degree j (A_j integr.).*
- Known results for A_3 integrability conditions:

weakly dispersive nonlinear systems: *KdV/pot.KdV* hierarchies,

strongly dispersive nonlinear systems: *NLS* hierarchy,

their *linearizable* limits.

Multiscale on the lattice: from shifts to derivatives

Let us consider a function $u_n : \mathbb{Z} \rightarrow \mathbb{R}$ depending on a discrete index $n \in \mathbb{Z}$

- The dependence of u_n on n is realized through the *slow variable* $n_1 \doteq \varepsilon n \in \mathbb{R}$, $\varepsilon \in \mathbb{R}$, $\varepsilon = 1/N$, $N \gg 0$, $0 < \varepsilon \ll 1$, that is to say $u_n \doteq u(n_1)$;
- The variable n_1 can vary in a region of the integer axis such that $u(n_1)$ is therein analytical (Taylor series expandible);
- The radius of convergence of the Taylor series in n_1 is wide enough to include as *inner points* the points $n_1 \pm k\varepsilon$.

$$T_n u_n \doteq u_{n+1} = u(n_1 + \varepsilon),$$

$$T_n u(n_1) = u(n_1) + \varepsilon u^{(1)}(n_1) + \frac{\varepsilon^2}{2} u^{(2)}(n_1) + \dots + \frac{\varepsilon^i}{i!} u^{(i)}(n_1) + \dots = e^{\varepsilon d_{n_1}} u(n_1),$$

$$u_n \doteq u(n, n_1), \quad T_n = \mathcal{T}_n \mathcal{T}_{n_1}^{(\varepsilon n_1)} = \mathcal{T}_n \sum_{j=0}^{+\infty} \varepsilon^j \mathcal{A}_n^{(j)}, \quad \mathcal{A}_n^{(j)} \doteq \frac{N_1^j}{j!} \partial_{n_1}^j, \quad (1)$$

$$u \left(n, m, n_1, \{m_j\}_{j=1}^K, \varepsilon \right) = \sum_{\gamma=1}^{+\infty} \sum_{\alpha=-\gamma}^{\gamma} \varepsilon^\gamma u_\gamma^{(\alpha)} \left(n_1, \{m_j\}_{j=1}^K \right) E_{n,m}^\alpha, \quad (2)$$

$$E_{n,m} \doteq e^{i[\kappa n - \omega(\kappa)m]}, \quad u_\gamma^{(-\alpha)} = \bar{u}_\gamma^{(\alpha)}$$

Multiscale on the lattice: from derivatives to shifts

Our multiscale approach produces from a given partial difference equation a partial differential equation for one of the amplitudes $u_\gamma^{(\alpha)}$. From the PDE we get a P Δ E inverting the shift operator.

$$\partial_{n_1} = \ln \mathcal{T}_{n_1} = \ln \left(1 + h_1 \Delta_{n_1}^{(+)} \right) \doteq \sum_{i=1}^{+\infty} \frac{(-1)^{i-1} h_1^i}{i} \Delta_{n_1}^{(+i)}, \quad (3)$$

where $\Delta_{n_1}^{(+)} \doteq \frac{\mathcal{T}_{n_1} - 1}{h_1}$ is *forward* difference operator in n_1 .

$$\Delta_{n_1}^j u_{n_1} \doteq \sum_{i=0}^j (-1)^{j-i} \binom{j}{i} u_{n_1+i} = \sum_{i=j}^{\infty} \frac{j!}{i!} P_{i,j} \Delta_{n_1}^i u_{n_1}. \quad (4)$$

$$P_{i,j} \doteq \sum_{k=j}^i \Omega^k \mathcal{S}_i^k \mathcal{G}_k^j,$$

Ω is the ratio of the increment in the lattice of variable n with respect to that of variable n_1 . The coefficients \mathcal{S}_i^k and \mathcal{G}_k^j are the Stirling numbers of the first and second kind respectively.

Multiscale on the lattice: from derivatives to shifts

This is one of the possible inversion formulae for \mathcal{T}_{n_1} . Ex. for *symmetric* difference operator $\Delta_{n_1}^{(s)} \doteq (\mathcal{T}_{n_1} - \mathcal{T}_{n_1}^{-1}) / 2h_1$ we get

$$\partial_{n_1} = \sinh^{-1} h_1 \Delta_{n_1}^{(s)} \doteq \sum_{i=1}^{+\infty} \frac{P_{i-1}(0) h_1^i}{i} \Delta_{n_1}^{(s)i}, \quad (5)$$

where $P_i(0)$ is the i -th *Legendre* polynomial evaluated in $x = 0$.

Difference equations of ∞ order. Only if u_n is a slow-varying function of order l , i.e.

$$\Delta^{l+1} u_n \approx 0$$

∂_{n_1} operator reduces to polynomials in the Δ_{n_1} of order at most l .

Integrability of discrete *NLS* equations (*dNLS*)

- The nonintegrable standard *dNLSE*

$$i\dot{u}_n + \frac{1}{2\sigma^2} (u_{n+1} - 2u_n + u_{n-1}) = \varepsilon |u_n|^2 u_n, \quad \varepsilon \doteq \pm 1, \quad (6)$$

- The integrable Ablowitz-Ladik *dNLSE*

$$i\dot{u}_n + \frac{1}{2\sigma^2} (u_{n+1} - 2u_n + u_{n-1}) = \varepsilon |u_n|^2 (u_{n+1} + u_{n-1}), \quad \varepsilon \doteq \pm 1, \quad (7)$$

- The saturable *dNLSE*

$$i\dot{u}_n + \frac{1}{2\sigma^2} (u_{n+1} - 2u_n + u_{n-1}) = \frac{|u_n|^2}{\varepsilon + |u_n|^2} u_n, \quad \varepsilon \doteq \pm 1, \quad (8)$$

- The Salerno *dNLSE*

$$i\dot{u}_n + \frac{1}{2\sigma^2} (u_{n+1} - 2u_n + u_{n-1}) (1 - s\varepsilon\sigma^2 |u_n|^2) = \varepsilon |u_n|^2 u_n, \quad \varepsilon \doteq \pm 1, \quad s \in \mathcal{R}, \quad (9)$$

interpolates between Eq. (6) when $s = 0$ and Eq. (7) when $s = 1$.

Integrability of discrete *NLS* equations (*dNLS*)

- Differential-difference equation example:

$$i\dot{u}_n + \frac{1}{2\sigma^2} (u_{n+1} - 2u_n + u_{n-1}) = |u_n|^2 (\beta_1 u_n + \beta_2 u_{n+1} + \beta_3 u_{n-1}) + |u_n|^4 (\theta_1 u_n + \theta_2 u_{n+1} + \theta_3 u_{n-1}),$$

Ablowitz-Ladik integr. *dNLS* when $\beta_1 = \theta_1 = \theta_2 = \theta_3 = 0$ and $\beta_2 = \beta_3 = \varepsilon$;
the standard **nonintegrable *dNLS*** when $\beta_2 = \beta_3 = \theta_1 = \theta_2 = \theta_3 = 0$, and $\beta_1 = \varepsilon$;

the first term of the small amplitude approximation of the **saturable *dNLS*** when $\beta_1 = \varepsilon$, $\theta_1 = -1$ and $\beta_j = \theta_j = 0$, $j = 2, 3$;

the **Salerno *dNLS*** when $\beta_1 = \varepsilon(1 - s)$ and $\beta_2 = \beta_3 = \varepsilon s/2$.

Integrability of discrete *NLS* equations (*dNLS*)

- Solution of the form:

$$u_n(t; \varepsilon) = \sum_{j=1}^{+\infty} \sum_{\alpha=-j}^j \varepsilon^j f_j^{(\alpha)}(n_1, t_1, t_2, \dots) e^{i\alpha(\kappa n - \omega t)}.$$

Expansion Parameters

- 1 $0 \leq \varepsilon \ll 1$: perturbative parameter around plane wave solution of *dNLS*;
- 2 $n_1 \doteq \varepsilon n$: slow “space” variable;
- 3 $t_j = \varepsilon^j t, j \geq 1$ slow times variables;

- $f_j^{(\alpha)}(n_1, t_1, t_2, \dots) \in \mathcal{C}^{(\infty)}$ in n_1 :

$$f_j^{(\alpha)}(n_1 \pm \varepsilon) = f_j^{(\alpha)}(n_1) \pm \varepsilon \partial_{n_1} f_j^{(\alpha)} + \frac{(\varepsilon \partial_{n_1})^2}{2} f_j^{(\alpha)} + \dots \doteq e^{\pm \varepsilon \partial_{n_1}} f_j^{(\alpha)};$$

$$f_{n \pm 1}(t; \varepsilon) = \sum_{j=1}^{+\infty} \sum_{\alpha=-j}^j \sum_{\rho=\max\{1, |\alpha|\}}^j \varepsilon^j \left(\mathcal{A}_{j-\rho}^{\pm} f_{\rho}^{(\alpha)} \right) e^{i\alpha[\kappa(n \pm 1) - \omega t]};$$

Expansion Operators

- 1 $\mathcal{A}_{\kappa}^{\pm} \doteq (\pm \partial_{n_1})^{\kappa} / \kappa!$: from shift operators as series of derivatives;
- 2 ∂_{n_1} : derivative operator w. r. t. n_1 (continuous through $\mathcal{C}^{(\infty)}$) with derivatives calculated in $n_1 = \varepsilon n$;

- Similar expansion for the time derivative:

$$\partial_t f_n(t; \varepsilon) = -i\omega f_n + \sum_{j=2}^{+\infty} \sum_{\alpha=-(j-1)}^{j-1} \sum_{\rho=\max\{1, |\alpha|\}}^{j-1} \varepsilon^j \left(\partial_{t_{j-\rho}} f_\rho^{(\alpha)} \right) e^{i\alpha(\kappa n - \omega t)};$$

The reduced equations

Plug everything into the *dNLS*:

- Order ε :

$\alpha = 1$: dispersion relation

$$\omega = \frac{1 - \cos(\kappa)}{\sigma^2};$$

$\alpha = -1$:

$$f_1^{(-1)} = 0;$$

- Order ε^2 :

$\alpha = 1$: group velocity

$$\partial_{t_1} f_1^{(1)} + \frac{\sin(\kappa)}{\sigma^2} \partial_{n_1} f_1^{(1)} = 0, \quad f_1^{(1)} \left(n_1 - \frac{\sin(\kappa)}{\sigma^2} t_1 \right);$$

$\alpha = 0, -1, \pm 2$:

$$f_1^{(0)} = f_2^{(-1)} = f_2^{(\pm 2)} = 0;$$

- Order ε^3 :
 $\alpha = 1$:

$$\partial_{t_1} f_2^{(1)} + \frac{\sin(\kappa)}{\sigma^2} \partial_{n_1} f_2^{(1)} = -\partial_{t_2} f_1^{(1)} + \frac{i \cos(\kappa)}{2\sigma^2} \partial_{n_1}^2 f_1^{(1)} - i\rho_2 f_1^{(1)} |f_1^{(1)}|^2,$$

$$\rho_2 \doteq [\beta_1 + (\beta_2 + \beta_3) \cos(\kappa) + i(\beta_2 - \beta_3) \sin(\kappa)] / N_2.$$

No-secularity conditions

- The right-hand side solves the homogeneous equation: **secularity!**

$$\partial_{t_1} f_2^{(1)} + \frac{\sin(\kappa)}{\sigma^2} \partial_{n_1} f_2^{(1)} = 0,$$

$$\partial_{t_2} f_1^{(1)} = K_2 \left[f_1^{(1)} \right],$$

$$K_2 \left[f_1^{(1)} \right] \doteq \frac{i \cos(\kappa)}{2\sigma^2} \partial_{n_1}^2 f_1^{(1)} - i\rho_2 f_1^{(1)} |f_1^{(1)}|^2 : \text{NLS equation!}$$

- A_1 -integrability condition: $\rho_2 \doteq [\beta_1 + (\beta_2 + \beta_3)] \cos(\kappa) + i(\beta_2 - \beta_3) \sin(\kappa)$ has to be real: it is satisfied iff $\beta_2 = \beta_3$.

Theorem of A_1 -integrability:

The dNLS equation

$$i\dot{u}_n + \frac{1}{2\sigma^2} (u_{n+1} - 2u_n + u_{n-1}) = |u_n|^2 (\beta_1 u_n + \beta_2 u_{n+1} + \beta_3 u_{n-1}) + |u_n|^4 (\theta_1 u_n + \theta_2 u_{n+1} + \theta_3 u_{n-1}),$$

is A_1 -integrable iff $\beta_2 = \beta_3$:

$$i\dot{u}_n + \frac{1}{2\sigma^2} (u_{n+1} - 2u_n + u_{n-1}) = |u_n|^2 (\beta_1 u_n + \beta_2 [u_{n+1} + u_{n-1}]) + |u_n|^4 (\theta_1 u_n + \theta_2 u_{n+1} + \theta_3 u_{n-1}),$$

$\alpha = 0, -1, \pm 2, \pm 3$:

$$f_2^{(0)} = f_3^{(-1)} = f_3^{(\pm 2)} = f_3^{(\pm 3)} = 0;$$

- Order ε^4 :

$\alpha = 1$:

$$\partial_{t_1} f_3^{(1)} + \frac{\sin(\kappa)}{\sigma^2} \partial_{n_1} f_3^{(1)} = i \left(\partial_{t_2} f_2^{(1)} - K_2' [f_1^{(1)}] f_2^{(1)} \right) + \\ + i \left(\partial_{t_3} f_1^{(1)} - K_3 [f_1^{(1)}] \right) - ia |f_1^{(1)}|^2 \partial_{n_1} f_1^{(1)},$$

$K_3 [f_1^{(1)}]$: flux of first higher order NLS symmetry (cmKdV),
 $a \doteq -\beta_1 \tan(\kappa)$;

No-secularity conditions 1

- The right-hand side solves the homogeneous equation: **secularity!**

$$\partial_{t_1} f_3^{(1)} + \frac{\sin(\kappa)}{\sigma^2} \partial_{n_1} f_3^{(1)} = 0,$$

$$\partial_{t_2} f_2^{(1)} - K_2' [f_1^{(1)}] f_2^{(1)} = a |f_1^{(1)}|^2 \partial_{n_1} f_1^{(1)} - \left(\partial_{t_3} f_1^{(1)} - K_3 [f_1^{(1)}] \right);$$

$$\partial_{t_2} f_2^{(1)} - K_2' [f_1^{(1)}] f_2^{(1)} = a |f_1^{(1)}|^2 \partial_{n_1} f_1^{(1)} - \left(\partial_{t_3} f_1^{(1)} - K_3 [f_1^{(1)}] \right);$$

No-secularity conditions 2

- The red highlighted term on right-hand side solves the homogeneous equation: **secularity!**

$$\partial_{t_3} f_1^{(1)} = K_3 [f_1^{(1)}],$$

$$\partial_{t_2} f_2^{(1)} - K_2' [f_1^{(1)}] f_2^{(1)} = a |f_1^{(1)}|^2 \partial_{n_1} f_1^{(1)};$$

- A_2 -integrability conditions:** $a \doteq -\beta_1 \tan(\kappa)$ has to be **real** \rightarrow **satisfied!**

Theorem of A_2 -integrability:

The dNLS equation

$$\begin{aligned} i\dot{u}_n + \frac{1}{2\sigma^2} (u_{n+1} - 2u_n + u_{n-1}) &= |u_n|^2 (\beta_1 u_n + \beta_2 (u_{n+1} + u_{n-1})) + \\ &+ |u_n|^4 (\theta_1 u_n + \theta_2 u_{n+1} + \theta_3 u_{n-1}), \end{aligned}$$

is A_2 -integrable $\forall \beta_1, \beta_2, \theta_i, i = 1, 2, 3$;

$\alpha = 0, -1, \pm 2, \pm 3, \pm 4$:

$$f_3^{(0)} = f_4^{(-1)} = f_4^{(\pm 2)} = f_4^{(\pm 3)} = f_4^{(\pm 4)} = 0;$$

- Order ε^5 :

$\alpha = 1$:

No-secularity conditions

$$\partial_{t_1} f_4^{(1)} + \frac{\sin(\kappa)}{\sigma^2} \partial_{n_1} f_4^{(1)} = 0,$$

$$\partial_{t_2} f_3^{(1)} - K_2' [f_1^{(1)}] f_3^{(1)} = g_2(3): \text{forced linearized NLS},$$

$$\partial_{t_3} f_2^{(1)} - K_3' [f_1^{(1)}] f_2^{(1)} = g_3(2): \text{forced linearized cmKdV},$$

$$\partial_{t_4} f_1^{(1)} = K_4 [f_1^{(1)}]: \text{flux of second higher order NLS symmetry};$$

- A_3 -integrability conditions (on the coefficient of $g_2(3)$):
 $\beta_1 = \theta_1 = \theta_2 = \theta_3 = 0 \rightarrow$ Ablowitz-Ladik!;

Theorem of A_3 -integrability:

The only dNLS belonging to our class

$$i\dot{u}_n + \frac{1}{2\sigma^2} (u_{n+1} - 2u_n + u_{n-1}) = |u_n|^2 (\beta_1 u_n + \beta_2 u_{n+1} + \beta_3 u_{n-1}) + |u_n|^4 (\theta_1 u_n + \theta_2 u_{n+1} + \theta_3 u_{n-1}),$$

being A_3 -integrable, is the Ablowitz-Ladik dNLS equation

$$i\partial_t u_n(t) + \frac{u_{n+1}(t) - 2u_n(t) + u_{n-1}(t)}{2\sigma^2} = \beta_2 |u_n(t)|^2 (u_{n+1}(t) + u_{n-1}(t)).$$

Other partial difference equations

- offcentrally discretized *KdV* equation: A_0 -asymptotically integrable!

$$u_2 - u_{-2} = \frac{\alpha}{4} [u_{111} - 3u_1 + 3u_{-1} - u_{-1-1-1}] - \frac{b}{2} [u_1^2 - u^2];$$

- symmetrically discretized *KdV* equation: A_2 -asymptotically integrable!

$$u_2 - u_{-2} = \frac{\alpha}{4} [u_{111} - 3u_1 + 3u_{-1} - u_{-1-1-1}] - \frac{b}{2} [u_1^2 - u_{-1}^2];$$

- *Zabusky-Kruskal KdV*

$$\dot{q}_n = \frac{1}{2h^3} (q_{n+2} - 2q_{n+1} + 2q_{n-1} - q_{n-2}) + \frac{1}{h} (q_{n+1} + q_n + q_{n-1})(q_{n+1} - q_{n-1})$$

A_2 -asymptotically integrable!

- *lpKdV* equation: A_3

$$\alpha (u_{n+1,m+1} - u_{n,m}) + \beta (u_{n+1,m} - u_{n,m+1}) - (u_{n+1,m} - u_{n,m+1})(u_{n+1,m+1} - u_{n,m}) = 0;$$

- *Hietarinta* equation (A_1 : linearizable $\rightarrow A_\infty$).

$$\frac{u_{n,m} + e_2}{u_{n,m} + e_1} \cdot \frac{u_{n+1,m+1} + o_2}{u_{n+1,m+1} + o_1} = \frac{u_{n+1,m} + e_2}{u_{n+1,m} + o_1} \cdot \frac{u_{n,m+1} + o_2}{u_{n,m+1} + e_1}.$$

Classification of lattice equations on the square

- Dispersive affine linear equation on the square:

$$\begin{aligned} & a_1(u_{n,m} + u_{n+1,m+1}) + a_2(u_{n+1,m} + u_{n,m+1}) + \\ & + (\alpha_1 - \alpha_2) u_{n,m} u_{n+1,m} + (\alpha_1 + \alpha_2) u_{n,m+1} u_{n+1,m+1} + \\ & + (\beta_1 - \beta_2) u_{n,m} u_{n,m+1} + (\beta_1 + \beta_2) u_{n+1,m} u_{n+1,m+1} + \\ & + \gamma_1 u_{n,m} u_{n+1,m+1} + \gamma_2 u_{n+1,m} u_{n,m+1} + \\ & + (\xi_1 - \xi_3) u_{n,m} u_{n+1,m} u_{n,m+1} + (\xi_1 + \xi_3) u_{n,m} u_{n+1,m} u_{n+1,m+1} + \\ & + (\xi_2 - \xi_4) u_{n+1,m} u_{n,m+1} u_{n+1,m+1} + (\xi_2 + \xi_4) u_{n,m} u_{n,m+1} u_{n+1,m+1} + \\ & + \zeta u_{n,m} u_{n+1,m} u_{n,m+1} u_{n+1,m+1} = 0, \end{aligned}$$

$a_1, a_2, \alpha_1, \alpha_2, \beta_1, \beta_2, \gamma_1, \gamma_2, \xi_1, \xi_2, \xi_3, \xi_4, \zeta$ real parameters and $|a_1| \neq |a_2|$.

- Linear dispersion relation:**

$$\omega(\kappa) = \arctan \left[\frac{(a_1^2 - a_2^2) \sin(\kappa)}{(a_1^2 + a_2^2) \cos(\kappa) + 2a_1 a_2} \right];$$

Theorem of A_1 -integrability: *The only A_1 -integrable eq. in our class are characterized by:*

• Case 1:

$$\left\{ \begin{array}{l} 2a_1 a_2 \alpha_1 = \gamma_1 a_2^2 + \gamma_2 a_1^2, \\ 2a_1 a_2 (a_1 - a_2) \beta_1 = (a_1 + a_2) (\gamma_2 a_1^2 - \gamma_1 a_2^2), \\ (a_2 + a_1) \beta_2 = (a_2 - a_1) \alpha_2, \\ (a_2^2 - a_1^2) (\xi_1 - \xi_2) = [\gamma_1 (a_1 - 3a_2) - \gamma_2 (a_2 - 3a_1)] \alpha_2, \\ (a_1 + a_2) (\xi_3 - \xi_4) = (\gamma_2 - \gamma_1) \alpha_2. \end{array} \right. \quad (10)$$

• Case 2:

$$\left\{ \begin{array}{l} 2a_1 a_2 (a_1 - a_2) \alpha_1 = (a_1 + a_2) (\gamma_2 a_1^2 - \gamma_1 a_2^2), \\ 2a_1 a_2 \beta_1 = \gamma_1 a_2^2 + \gamma_2 a_1^2, \\ (a_2 - a_1) \beta_2 = (a_2 + a_1) \alpha_2, \\ (a_2 - a_1) (\xi_1 - \xi_2) = (\gamma_1 - \gamma_2) \alpha_2, \\ (a_2 - a_1)^2 (\xi_3 - \xi_4) = [\gamma_2 (a_2 - 3a_1) - \gamma_1 (a_1 - 3a_2)] \alpha_2. \end{array} \right. \quad (11)$$

Theorem of A_1 -integrability: (cont.)

- Case 3:

$$\begin{cases} \gamma_1 a_2 = \gamma_2 a_1, \\ \alpha_1 = \beta_1 = \frac{1}{2}(\gamma_1 + \gamma_2), \\ a_1(\xi_1 - \xi_2) = -\alpha_2 \gamma_1, \\ a_1(\xi_3 - \xi_4) = \beta_2 \gamma_1. \end{cases} \quad (12)$$

- Case 4:

$$\begin{cases} \alpha_2 = \beta_2 = 0, \\ \xi_1 = \xi_2, \\ \xi_3 = \xi_4. \end{cases} \quad (13)$$

Theorem of A_1 -integrability: (cont.)

- Case 5:

$$\left\{ \begin{array}{l} a_2 = 2a_1, \\ \alpha_1 = \beta_1, \\ \alpha_2 = -\beta_2, \\ \gamma_2 = 2\gamma_1, \\ a_1(\xi_1 - \xi_2) = a_1(\xi_3 - \xi_4) = -\alpha_2\gamma_1. \end{array} \right. \quad (14)$$

- Case 6:

$$\left\{ \begin{array}{l} a_1 = 2a_2, \\ \alpha_1 = \beta_1, \\ \alpha_2 = \beta_2, \\ \gamma_1 = 2\gamma_2, \\ a_1(\xi_1 - \xi_2) = -a_1(\xi_3 - \xi_4) = -\alpha_2\gamma_1. \end{array} \right. \quad (15)$$

Conclusions

- 1 *Integrability test* suitable for a large variety of nonlinear systems;
- 2 We have shown that among a class of *dNLS* equations considered in the literature *only the Ablowitz-Ladik dNLS* is integrable;
- 3 A_1 -classification of dispersive affine linear equation on the square.

Open problems

- What happens if we do not require the $C^{(\infty)}$ property of solutions: can we still get *discrete integrable systems*;
- Extend to other discrete systems as *weakly dissipative* systems: *Burgers* hierarchy;
- Find the appropriate *normal form* theory for discrete equations;

Open problems

- In the A_1 -classification of dispersive affine linear equation on the square one equation emerges as a possibly integrable equation:

$$\begin{aligned} & a_1[u_{n,m} + u_{n+1,m+1} + 2(u_{n+1,m} + u_{n,m+1})] + \\ & + 3\gamma_1 [u_{n,m}u_{n+1,m} + u_{n,m+1}u_{n+1,m+1} + u_{n,m}u_{n,m+1} + u_{n+1,m}u_{n+1,m+1}] \\ & + \gamma_1 [u_{n,m}u_{n+1,m+1} + 2u_{n+1,m}u_{n,m+1}] + \\ & + (\xi_1 - \xi_3) [u_{n,m}u_{n+1,m}u_{n,m+1} + u_{n+1,m}u_{n,m+1}u_{n+1,m+1}] + \\ & + (\xi_1 + \xi_3) [u_{n,m}u_{n+1,m}u_{n+1,m+1} + u_{n,m}u_{n,m+1}u_{n+1,m+1}] + \\ & + \zeta u_{n,m}u_{n+1,m}u_{n,m+1}u_{n+1,m+1} = 0, \end{aligned}$$

Analyze its A_3 integrability.

- Integrability test for *maps*;
- Dependence of degree of asymptotic integrability from the solutions used.

THANK YOU